# Comment on the Representation of Splines as Boolean Sums 

L. P. Bos and K. Salkauskas<br>Department of Mathematics and Statistics, University of Calgary, Calgary, Alberta, T2N 1N4, Canada<br>Communicated by Charles K. Chui

Received March 14, 1986

## 1. Introduction

In the past few years, Boolean sums of interpolating projectors have figured prominently in the formulation of blended interpolation, pioneered by, for example, Gordon and Hall [3,4], and in the representation of some finite elements. More recently, Boolean sums have been used to obtain other types of interpolants, including splines.

Generally, if $P: X \rightarrow \operatorname{Im} P$ and $Q: X \rightarrow \operatorname{Im} Q$ are projectors, with $\operatorname{Im} Q \subset X$, then the Boolean sum $P \oplus Q$ is defined by $(P \oplus Q) f=$ $P(f-Q f)+Q f, \forall f \in X$, and $(P \oplus Q) f \in \operatorname{Im} P \oplus \operatorname{Im} Q$. Further, if $\operatorname{Im} P \subset X$ and $Q P=Q$, then $P \oplus Q$ is again a projector. In our applications $X$ is usually a function space, $\operatorname{Im} P \cap \operatorname{Im} Q=\varnothing$, both $\operatorname{Im} P$ and $\operatorname{Im} Q$ being subsets, or more frequently subspaces, of $X$.

In the blending context, take $X=C\{[a, b] \times[c, d]\}$. The intervals are partitioned so that $a=x_{1}<x_{2}<\cdots<x_{m}=b, c=y_{1}<y_{2}<\cdots<y_{n}=d$. Let $P_{x}$ and $P_{y}$ be interpolating projectors on $X$ in the sense that, for $f \in X$,
$\left(P_{x} f\right)\left(x_{i}, y\right)=f\left(x_{i}, y\right), \quad\left(P_{y} f\right)\left(x, y_{j}\right)=f\left(x, y_{j}\right), \quad i=1, \ldots, m ; j=1, \ldots, n$.
It is then found that $P_{x} \oplus P_{y}$ is a projector with the "transfinite" interpolation property

$$
\begin{aligned}
&\left.\left(P_{x} \oplus P_{y}\right) f\right|_{x=x_{i}}=f\left(x_{i}, \cdot\right),\left.\quad\left(P_{x} \oplus P_{y}\right) f\right|_{y=y_{j}}=f\left(\cdot, y_{j}\right) \\
& i=1, \ldots, m ; j=1, \ldots, n .
\end{aligned}
$$

Another application of Boolean sums occurs in the improvement of the approximating properties of interpolating projectors. For example, one may have an interpolating projector $P$ on a function space $X$ containing
$\mathscr{P}_{1}$, such that Im $P$ does not contain $\mathscr{P}_{1}$. If $Q: X \rightarrow \mathscr{P}_{1}$ is a projector and $Q P=Q$, then $P \oplus Q$ is an interpolating projector with the additional property $(P \oplus Q) f=f, \forall f \in \mathscr{P}_{1}$.

Boolean sums also occur implicitly in kriging, a term used by geostatisticians for a process of estimating the value of a function (of two variables) at a point $x_{0}$, in terms of known values at other points $x_{i}$. In one of its formulations it can be shown that kriging involves an interpolating projector $P$ whose image is the linear span of functions $\varphi_{i}$ which are translates to the $x_{i}$ of a basic function $\varphi$. The latter is a generalized covariance which happens to also be a function. Quite often, $\varphi(x, y)=\left\{x^{2}+y^{2}\right\}^{1 / 2}$; $\varphi(x, y)=\left\{x^{2}+y^{2}\right\}^{3 / 2}$ is also used. The projector $Q$ is of weighted leastsquares type, but with an indefinite weight matrix, and $\operatorname{Im} Q=\mathscr{P}_{m}$, where $m$ is typically 0 or 1 .

Surface splines, as developed, for example, by Duchon [2] and Meinguet [6], can be expressed as Boolean sums much as in the kriging method. Some preliminary studies of this connection have been announced by Salkauskas [8]; a more thorough and profound account of the formal equivalence of kriging and surface splines is given by Matheron [5].

While the above are most often applied in the bivariate case, there are interesting formulations of univariate splines as Boolean sums. For example, most $C^{2}$ piecewise cubic spline interpolants of $f \in X$ can be represented as $(P \oplus Q) f$, where $P: X \rightarrow \operatorname{span}\left\{\left|x-x_{i}\right|^{3}\right\}_{i=1}^{n}$ is an interpolating projector, and $Q$ is a certain projector onto $\mathscr{P}_{1}$. In the sequel we discuss properties of the above, as well as generalizations to higher-degree univariate splines. Since our projectors always sample $f \in X$ at $n$ distinct points $x_{i}$, it will be sufficient to assume that $X=\mathbb{R}^{n}$. Also, it is clear that now $Q P \mathbf{f}=Q \mathbf{f}$, for $Q$ "sees" the same values in $P \mathrm{f}$ as in f . Consequently $P \oplus Q$ will always be a projector.

## 2. Univariate Splines as Boolean Sums

Suppose that $x_{1}<x_{2}<\cdots<x_{n}$ are given. In [1] it is shown that the matrices

$$
V=\left[\left|x_{i}-x_{j}\right|^{2 k+1}\right]_{1 \leqslant i, j \leqslant n}
$$

are non-singular. We will assume that $n>2 k-1$. Hence for any $\mathbf{f} \in \mathbb{R}^{n}$ there is a unique $\mathbf{c} \in \mathbb{R}^{n}$ such that $s(x)=\sum_{j=1}^{n} c_{j}\left|x-x_{j}\right|^{2 k+1}$ interpolates the given data, i.e., $s\left(x_{i}\right)=f_{i}, i=1, \ldots, n$. The corresponding interpolating projector may be represented as

$$
\begin{equation*}
P \mathbf{f}=\left[\left|x-x_{1}\right|^{2 k+1},\left|x-x_{2}\right|^{2 k+1}, \ldots,\left|x-x_{n}\right|^{2 k+1}\right] V^{-1} \mathbf{f} . \tag{2.0}
\end{equation*}
$$

We see that $P \mathbf{f}$ is piecewise polynomial of degree $2 k+1$ with knots $x_{1}, \ldots, x_{n}$ and of continuity class $C^{2 k}$.

Now let $B=\left[x_{i}^{j-1}\right]_{1 \leqslant i \leqslant n, 1 \leqslant j \leqslant 2 k}$ and for $W \in \mathbb{R}^{n \times n}$ positive definite on the image of $B$, let $Q_{w}$ be the corresponding weighted least-squares projector defined by

$$
Q_{W} \mathbf{f}=\left[1, x, \ldots, x^{2 k-1}\right]\left(B^{t} W B\right)^{-1} B^{t} W \mathbf{f} \in \mathscr{P}_{2 k-1} .
$$

Theorem 2.1. Let $s(x)$ be a spline of degree ( $2 k+1$ ) with knots $x_{1}<x_{2}<\cdots<x_{n}$ and $\mathbf{s} \in \mathbb{R}^{n}$ be the vector of function values of $s(x)$ at the knots. If $\mathbf{s} \notin \operatorname{Im} B$, i.e., $\mathbf{s}$ is not polynomial of degree ( $2 k-1$ ), then there exists a $W$, positive definite on $\operatorname{Im} B$, such that

$$
\begin{equation*}
s(x)=\left(P \oplus Q_{W}\right) \mathbf{s} . \tag{2.1}
\end{equation*}
$$

Further, if $\mathbf{s} \in \operatorname{Im} B$ then there exists a $W$ for which (2.1) holds if and only if $s(x)$ is itself a polynomial of degree $2 k-1$.

Proof. As $s(x)$ is a spline of degree $(2 k+1), s^{(2 k)}(x)$ must be piecewise linear with knots $x_{1}<x_{2}<\cdots<x_{n}$. Hence there are coefficients $\alpha_{i}$ such that

$$
s^{(2 k)}(x)=\sum_{i=1}^{n} \alpha_{i}\left|x-x_{i}\right| .
$$

Upon integrating $2 k$ times, we see that

$$
\begin{equation*}
s(x)=\sum_{j=1}^{n} c_{j}\left|x-x_{j}\right|^{2 k+1}+\sum_{j=0}^{2 k-1} a_{j} x^{j} \tag{2.2}
\end{equation*}
$$

for some coefficients $c_{j}$ and $a_{j}$. Therefore,

$$
\begin{equation*}
\mathbf{s}=V \mathbf{c}+B \mathbf{a} . \tag{2.3}
\end{equation*}
$$

Now, explicitly,

$$
\begin{align*}
P \oplus Q_{W} \mathbf{s}= & {\left[\left|x-x_{1}\right|^{2 k+1}, \ldots,\left|x-x_{n}\right|^{2 k+1}\right] V^{-1}(I-B M) \mathbf{s} } \\
& +\left[1, x, \ldots, x^{2 k-1}\right] M \mathbf{s} . \tag{2.4}
\end{align*}
$$

where

$$
M=\left(B^{t} W B\right)^{-1} B^{t} W
$$

Comparing (2.2) with (2.4) we see that $s=P \oplus Q_{W} \mathbf{s}$ if

$$
V^{-1}(I-B M) \mathbf{s}=\mathbf{c} \quad \text { and } \quad B M \mathbf{s}=B \mathbf{a}
$$

or equivalently,

$$
(I-B M) \mathbf{s}=V \mathbf{c} \quad \text { and } \quad B M \mathbf{s}=B \mathbf{a} .
$$

But by (2.3), $V \mathbf{c}=\mathbf{s}-B \mathbf{a}$ and so $s=P \oplus Q_{W} \mathbf{s}$ if

$$
(I-B M) \mathbf{s}=\mathbf{s}-B \mathbf{a} \quad \text { and } \quad B M \mathbf{s}=B \mathbf{a},
$$

which reduces to the single condition

$$
B M \mathbf{s}=B \mathbf{a},
$$

which itself, as $B$ is of full rank, reduces to the condition

$$
M \mathbf{s}=\mathbf{a}
$$

If $\mathbf{s} \in \operatorname{Im} B$, that is, $\mathbf{s}=\boldsymbol{B} \mathbf{b}$, then

$$
M \mathrm{~s}=\left(B^{t} W B\right)^{-1} B^{t} W B \mathbf{b}=\mathbf{b}
$$

and

$$
(I-B M) \mathbf{s}=B \mathbf{b}-B \mathbf{b}=\mathbf{0},
$$

so that by (2.4), $s=P \oplus Q_{W^{\prime}}$ s only if $s(x)=\left[1, x, \ldots, x^{2 k-1}\right] M \mathrm{~s}$, i.e., $s(x)$ is a polynomial of degree $(2 k-1)$. Clearly, in this case any positive definite $W$ provides $s=P \oplus Q_{W} \mathbf{s}$.

If $s \notin \operatorname{Im} B$, we must show that a $W$ may be found such that $M s=a$. But there are certainly many matrices, $A \in \mathbb{R}^{2 k \times n}$ (recall that we assume that $n>2 k-1$ ), with the property that

$$
A B=I_{2 k} \quad \text { and } \quad A \mathbf{s}=\mathbf{a}
$$

Let $W=A^{t} A$. If $\mathbf{x}=B \mathbf{b} \in \operatorname{Im} B$ then $\mathbf{x}^{t} W \mathbf{x}=\mathbf{b}^{t} B^{t} A^{t} A B \mathbf{b}=\mathbf{b}^{t} I_{2 k}^{t} I_{2 k} \mathbf{b}=\mathbf{b}^{\prime} \mathbf{b}$ and $W$ is positive definite on $\operatorname{Im} B$. Further,

$$
\begin{aligned}
\left(B^{t} W B\right)^{-1} B^{t} W \mathbf{s} & =\left(B^{t} A^{t} A B\right)^{-1} B^{t} A^{t} A \mathbf{s} \\
& =\left((A B)^{t} A B\right)^{-1}(A B)^{t} \mathbf{a} \\
& =I_{2 k}^{-1} I_{2 k}^{t} \mathbf{a} \\
& =\mathbf{a} .
\end{aligned}
$$

The result follows.
In the case of natural splines there is a somewhat more specific result concerning the weight matrix $W$ of the projector $Q$, preliminary to which we require the following two lemmas. Let $C=\left[x_{i}^{j-1}\right]_{1 \leqslant i \leqslant n, 1 \leqslant j \leqslant k+1} . C$ resembles $B$ (in fact they are equal when $k=1$ ) but includes monomials up to degree $k$ only.

Lemma 2.2. $(-1)^{k-1} V$ is positive definite on the kernel of $C^{t}$.
Remark. This is a special case of the results of Micchelli [7]. We would, however, offer the following completely elementary proof.

Proof. Let $\mathbf{0} \neq \mathbf{c} \in N\left(C^{t}\right)$ and $s(x)=\sum_{i=1}^{n} c_{i}\left|x-x_{i}\right|^{2 k+1}$. Now an easy calculation shows that for $k+1 \leqslant j \leqslant 2 k, s^{(j)}\left(x_{1}\right)=s^{(j)}\left(x_{n}\right)=0$, that is, $s(x)$ is a natural spline. We now integrate $\int_{x_{1}}^{x_{n}}\left(s^{(k+1)}(x)\right)^{2} d x$, by parts, $k$ times. By the natural spline end conditions we have

$$
\begin{aligned}
& \int_{x_{1}}^{x_{n}} s^{(k+1)}(x) s^{(k+1)}(x) d x \\
&=(-1)^{k} \sum_{j=1}^{n-1} \int_{x_{j}}^{x_{j+1}} s^{(1)}(x) s^{(2 k+1)}(x) d x \\
&=\left.(-1)^{k} \sum_{j=1}^{n-1} s^{(2 k+1)}\right|_{\left(x_{j}, x_{j+1}\right)} \int_{x_{j}}^{x_{j+1}} s^{(1)}(x) d x \\
&=\left.(-1)^{k} \sum_{j=1}^{n-1} s^{(2 k+1)}\right|_{\left(x_{j}, x_{j+1}\right)}\left(s\left(x_{j+1}\right)-s\left(x_{j}\right)\right) .
\end{aligned}
$$

A manipulation of the sum gives, for the above,

$$
(-1)^{k-1} \sum_{j=1}^{n} s\left(x_{j}\right)\left\{\text { jump in } s^{(2 k+1)} \text { at } x_{j}\right\} .
$$

But an elementary calculation reveals that $\left\{\right.$ jump in $s^{(2 k+1)}$ at $\left.x_{j}\right\}=$ $2(2 k+1)!c_{j}$ and we see that

$$
2(-1)^{k-1}(2 k+1)!\sum_{j=1}^{n} c_{j} s\left(x_{j}\right)=\int_{x_{1}}^{x_{n}}\left(s^{(k+1)}(x)\right)^{2} d x
$$

As $\mathbf{c} \neq \mathbf{0}, s(x)$ is certainly not a polynomial of degree $k$ and hence

$$
\int_{x_{1}}^{x_{n}}\left(s^{(k+1)}(x)\right)^{2} d x>0
$$

Now recall the definitions of $s(x)$ and the matrix $V$ and notice that

$$
\mathbf{c}^{\prime} V \mathbf{c}=\sum_{j=1}^{n} c_{j} s\left(x_{j}\right)
$$

The result follows.

Lemma 2.3. The matrix $C^{t} V^{-1} C$ is invertible.
Proof. Suppose that $C^{t} V^{-1} C \mathbf{x}=\mathbf{0}$. Let $\mathbf{c}=V^{-1} C \mathbf{x}$. Then $C^{t} \mathbf{c}=\mathbf{0}$, that is, $c \in N\left(C^{t}\right)$ and

$$
\begin{aligned}
\mathbf{c}^{t} V \mathbf{c} & =\mathbf{x}^{t} C^{t} V^{-1} V V^{-1} C \mathbf{x} \\
& =\mathbf{x}^{t} C^{t} V^{-1} C \mathbf{x} \\
& =\mathbf{x}^{t} \mathbf{0}=0
\end{aligned}
$$

Hence by Lemma 2.2, $\mathbf{c}=\mathbf{0}$ and therefore $C \mathbf{x}=\mathbf{0}$. But $C$ is of full rank and so $\mathbf{x}=\mathbf{0}$.

With $P$ as in (2.0), let $Q$ now represent a projector onto the polynomials of degree $k$ given by

$$
Q \mathbf{f}=\left[1, x, \ldots, x^{k}\right] M \mathbf{f}
$$

where $M \in \mathbb{R}^{(k+1) \times n}$ is such that $M C=I_{k+1}$.

Theorem 2.4. The representation $s(x)=(P \oplus Q) \mathbf{s}$ holds for all natural splines, $s(x)$, of degree $(2 k+1)$ with knots $x_{1}<x_{2}<\cdots<x_{n}$ if and only if $M=\left(C^{t} V^{-1} C\right)^{-1} C^{t} V^{-1}$, that is, $Q$ is the least-squares projector with weight $W=V^{-1}$.

Proof. First suppose that $M=\left(C^{t} V^{-1} C\right)^{-1} C^{t} V^{-1}$. Consider any natural spline $s(x)$. Let $t(x)=P \oplus Q s=\left[\left|x-x_{1}\right|^{2 k+1}, \ldots,\left|x-x_{n}\right|^{2 k+1}\right]$ $V^{-1}(I-C M) \mathbf{s}+\left[1, x, \ldots, x^{k}\right] M \mathrm{~s}$. By the uniqueness of natural interpolating splines we need only show that $t(x)$ interpolates $s(x)$ and that $t(x)$ is natural. It is clear that $t(x)$ interpolates. To show that $t(x)$ is natural, write

$$
t(x)=\sum_{j=1}^{n} c_{j}\left|x-x_{j}\right|^{2 k+1}+\sum_{j=0}^{k} a_{j} x^{j}
$$

where $\mathbf{c}=V^{-1}(I-C M) \mathbf{s}$ and $\mathbf{a}=M \mathbf{s}$. As was stated in the proof of Lemma 2.2, $t(x)$ is natural if $\mathbf{c} \in N\left(C^{t}\right)$. But

$$
\begin{aligned}
C^{t} \mathbf{c} & =C^{t} V^{-1}(I-C M) \mathbf{s} \\
& =C^{t} V^{-1}\left(I-C\left(C^{t} V^{-1} C\right)^{-1} C^{t} V^{-1}\right) \mathbf{s} \\
& =C^{t} V^{-1} \mathbf{s}-\left(C^{t} V^{-1} C\right)\left(C^{t} V^{-1} C\right)^{-1} C^{t} V^{-1} \mathbf{s} \\
& =C^{t} V^{-1} \mathbf{s}-C^{t} V^{-1} \mathbf{s}=\mathbf{0}
\end{aligned}
$$

Conversely, if $s(x)=P \oplus Q s$ is natural then again we must have $0=C^{t} \mathbf{c}=$ $C^{t} V^{-1}(I-C M) \mathbf{s}=C^{t} V^{-1} s-\left(C^{t} V^{-1} C\right) M \mathrm{~s}$. Hence, as $C^{t} V^{-1} C$ is nonsingular,

$$
M \mathrm{~s}=\left(C^{t} V^{-1} C\right)^{-1} C^{t} V^{-1} \mathbf{s}
$$

Since $s \in \mathbb{R}^{n}$ is arbitrary we must have

$$
M=\left(C^{t} V^{-1} C\right)^{-1} C^{t} V^{-1}
$$

## References

1. N. Dyn, T. Goodman, and C. A. Micchell, Positive powers of certain conditionally negative definite matrices, Proc. Neth. Acad. Sci., in press.
2. J. Duchon, Splines minimizing rotation invariant semi-norms in Sobolev spaces, in "Constructive Theory of Functions of Several Variables" (W. Schempp and K. Zeller, Eds.), 571, Springer-Verlag, New York, 1977.
3. W. J. Gordon, Spline-blended surface interpolation through curve networks, J. Math. Mech. 18 (1969), 931-952.
4. W. J. Gordon and C. Hall, Geometric aspects of the finite element method, in "The Mathematical Foundations of the Finite Element Method with Applications to Partial Differential Equations" (K. Aziz, Ed.), Academic Press, New York, 1972.
5. G. Matheron, Splines and kriging: Their formal equivalence, in "Down-to-Earth Statistics: Solutions Looking for Geological Problems" (D. F. Merriam, Ed.), Syracuse University Geology Contribution 8, 1981.
6. J. Meinguet, Multivariate interpolation at arbitrary points made simple, Z. Angew. Math. Phys. 30 (1979), 292-304.
7. C. A. Micchelli, Interpolation of scattered data: Distance matrices and conditionally positive definite functions, Constr. Approx. 2(1) (1986), 11-22.
8. K. Salkauskas, Some relationships between surface splines and kriging, in "Multivariate Approximation Theory II" (W. Schempp and K. Zeller, Eds.), ISNM 61, Birkhäuser, Boston, 1982.
